

## THE CRAY-1 COMPUTER SYSTEM



# THE CRAY - 1° COMPUTER SYSTEM

The Cray Research, Inc. CRAY-1 Computer System is a large-scale, general-purpose digital computer featuring vector as well as scalar processing, a 12.5 nanosecond clock period, and a 50 nanosecond memory cycle time. The CRAY-1 is capable of executing over 80 million floating point operations per second. Even higher rates are possible with programs that take advantage of the vector features of the computer.

The CRAY-1 is an effective host processor for local computer networks and time-sharing networks. Cray Research provides hardware and software interfaces that link the CRAY-1 with other manufacturer's computer systems. This approach allows users to add the CRAY-1 to existing computing facilities.

The CRAY-1 is particularly adapted to the needs of the scientific community and is especially useful in solving problems requiring the analysis and prediction of the behavior of physical phenomena through computer simulation. The fields of weather forecasting, aircraft design, nuclear research, geophysical research, and seismic analysis involve this process. For example, the movements of global air masses for weather forecasting, air flows over wing and airframe surfaces for aircraft design, and the movements of particles for nuclear research, all lend themselves to such simulations. In each scientific field, the equations are known but the solutions require extensive computations involving large quantities of data. The quality of a solution depends heavily on the number of data points that can be considered and the number of computations that can be performed. The CRAY-1 provides substantial increases with respect to both the number of data points and computations so that researchers can apply the CRAY-1 to problems not feasibly solvable in the past.

#### CONFIGURATION

The basic configuration of the CRAY-1 consists of the central processor unit (CPU), power and cooling equipment, one or more minicomputer consoles, and a mass storage (disk) subsystem. The CPU holds the computation, memory, and I/O sections of the computer. A minicomputer serves either as a maintenance control unit or a job entry station.

#### **INPUT/OUTPUT**

Input/output is via twenty-four I/O channels, twelve of which are input and twelve output. Any number of channels may be active at a given time. For a 16-bit channel, transfer rates of 160 million bits per second can be achieved. Higher rates are possible but in practice, the maximum transfer rate is limited by the speed of peripheral devices.



BASIC COMPUTER SYSTEM

Input/output and the CPU share memory access via a single port. I/O priority is sufficient to ensure maintaining the required transfer rates for the peripheral devices.

#### MEMORY

The CRAY-1 memory is constructed of 1024-bit LSI chips. Up to 1,048,576 (generally referred to as one million) 72-bit words are arranged in 16 banks. Up to 524,288 words can be arranged in 8 banks. A word consists of 64 data bits and 8 check bits. The bank cycle time, that is, the time required to remove or insert an element of data in memory, is 50 nanoseconds. This short cycle time provides an extremely efficient random-access memory. There is no inherent memory degradation for 16-bank memories with less than one million words of memory.

A single-error-correction double error detection (SECDED) network assures that data written into memory can be returned to the computation section with consistent precision. There are eight check bits per memory word.

Printed circuit board module with integrated circuits installed.



Integrated circuits used in the CRAY-1 computer.



P-GUT L

CRAY-1 computer shown with installed banks of printed circuit board modules.

Section of the CRAY-1 computer showing installation of printed circuit board modules. Data station (equipment

not manufactured by CRI) used in the operation of the CRAY-1.

#### **FACTS AND FIGURES**

of transistors)

High-density logic

Logic

CPU	All range of the second se
Instruction size	16 or 32 bits
Repertoire size	128 instruction codes
Clock period	12.5 nsec
Instruction stack/buffers	64 words (4096 bits)
Functional units	twelve:
	3 integer add
	1 integer multiply 2 shift
	2 logical
	1 floating add
	1 reciprocal approx.
	1 population count
Programmable registers	8x64 64-bit
	72 24-bit
	1 7-bit
Max. vector result rate	12.5 nsec / unit
FLOATING POINT COMPUTA	ATION RATES (results per second)
Addition	80 x 10 <sup>6</sup> / sec
Multiplication	80 x 10 <sup>6</sup> / sec
Division	25 x 10 <sup>6</sup> / sec
MEMORY	
Technology	bipolar semiconductor
Word length	72 bits (64 data, 8 SECDED)
Address space	4M words
Data path width (bits)	64 (1 word)
Cycle time	50 nsec.
Size	262,144 words
	or 1,048,576 words
Organization / interleave	16 banks (8 banks optional)
Maximum band width	80 x 10 <sup>6</sup> words / sec
	(5.1 x 10 <sup>9</sup> bits / sec)
Error checking	SECDED
PHYSICAL CHARACTERIST	ICS / ELECTRONIC TECHNOLOGY
Size of CPU cabinet	9 ft diameter base
	4.5 ft diameter center 6.5 ft height
Weight of mainframe	5.25 tons
Cooling	Freon
Plug-in modules	1662
Module types	113
PC boards	5 layer
Circuitry (aquivalent no	2.5M

ECL, 1 nsec.

SSI

#### COMPUTATION SECTION

The computation section as illustrated on page 4 is composed of instruction buffers, registers, and functional units which operate together to execute sequences of instructions.

#### Data structure

Internal character representation in the CRAY-1 is in ASCII with each 64-bit word able to accommodate eight characters.

Numeric representation is either in two's complement form (24-bit or 64-bit) or in 64-bit floating point form using a signed magnitude binary coefficient and a biased exponent. Exponent overflow and underflow is caused if the exponent is greater than  $57777_8$  or less than  $20000_8$ . Either of these conditions causes an interrupt except where the interrupt has been inhibited.



#### **DATA FORMATS**

#### Instruction set

The CRAY-1 executes 128 operation codes as either 16-bit (one parcel) or 32-bit (two-parcel) instructions. Operation codes provide for both scalar and vector processing.

In general, an instruction that references registers occupies one parcel; an instruction that references memory occupies two parcels. All of the arithmetic and logical instructions reference registers.

Floating point instructions provide for addition, subtraction, multiplication, and reciprocal approximation. The reciprocal approximation instruction allows for the computation of a floating point divide operation using a multiple instruction sequence.



COMPUTATION SECTION



#### INSTRUCTION FORMATS

Integer or fixed point operations are provided for as follows: integer addition, integer subtraction, and integer multiplication. An integer multiply operation produces a 24-bit result; additions and subtractions produce either 24-bit or 64-bit results. No integer divide instruction is provided. The operation can be accomplished through a software algorithm using floating point hardware.

The instruction set includes Boolean operations for OR, AND, and exclusive OR and for a mask-controlled merge operation. Shift operations allow the manipulation of 64- or 128-bit operands to produce a 64-bit result. Similar 64-bit arithmetic capability is provided for both scalar and vector processing. Full indexing capability allows the programmer to index throughout memory in either scalar or vector modes of processing. This allows matrix operations in vector mode to be performed on rows, on columns, or on the diagonal.

Instructions for scalar population and leading zero counts return bit counts based on S register contents to an A register. Corresponding instructions for vector operations are available as a special option.

#### Addressing

Instructions that reference data do so on a word basis. Instructions that alter the sequence of instructions being executed, that is, the branch instructions, reference parcels of words. In this case, the lower two bits of an address identify the location of an instruction parcel in a word.

#### Instruction buffers

All instructions are executed from four instruction buffers. each consisting of 64 16-bit registers. Associated with each instruction buffer is a base address register that is used to determine if the current instruction resides in a buffer. Since the four instruction buffers are large, substantial program segments can reside in them. Forward and backward branching within the buffers is possible and the program segments may be noncontiguous. When the current instruction does not reside in a buffer, one of the instruction buffers is filled from memory. Four memory words are transferred per clock period. The buffer that is filled is the one least recently filled, that is, the buffers are filled in rotation. To allow the current instruction to issue as soon as possible, the memory word containing the current instruction is among the first four transferred. A parcel counter register (P) points to the next parcel to exit from the buffers. Prior to issue, instruction parcels may be held in the next instruction parcel (NIP), lower instruction parcel (LIP) and current instruction parcel (CIP) registers.

#### **Operating registers**

The CRAY-1 has five sets of registers, three primary and two intermediate. Primary registers can be accessed directly by functional units. Intermediate registers are not accessible by functional units but act as buffers between primary registers and memory. The figure on page 4 represents the CRAY-1 registers and functional units. The 64 address and 64 scalar intermediate registers can be filled by block transfers from memory. Their purpose is to reduce memory references made by the scalar and address registers.

The eight address registers are each 24 bits and can be used to count loops, provide shift counts, and act as index registers in addition to their main use for memory references.

The eight 64-bit scalar registers in addition to contributing operands and receiving results for scalar operations can provide one operand for vector operations.

Each of the eight vector (V) registers is actually a set of 64 64-bit registers, called elements. The number of vector operations to be performed (that is, the vector length) determines how many of the elements of a register are used to supply operands in a vector set or receive results of the vector operation. The hardware accommodates vectors with lengths up to 64; longer vectors are handled by the software dividing the vector into 64-element segments and a remainder.

Associated with the vector registers are a 7-bit vector length register and a 64-bit vector mask register. The vector length register, as its name implies, determines the number of operations performed by a vector instruction. Each bit of the vector mask register corresponds to an element of a V register. The mask is used with vector merge and test instructions to allow operations to be performed on individual vector elements.

#### Supporting registers

In addition to the operating registers, the CPU contains a variety of auxiliary and control registers. For example, there is a channel address (CA) register and a channel limit register (CL) for each I/O channel.

#### **Functional units**

Instructions other than simple transmits or control operations are performed by hardware organizations known as functional units. Each of the twelve units in the CRAY-1 executes an algorithm or a portion of the instruction set. Units are independent. A number of functional units can be in operation at one time.

A functional unit receives operands from registers and delivers the result to a register when the function has been performed. The units operate essentially in three-address mode with source and destination addressing limited to register designators.

All functional units perform their algorithms in a fixed amount of time. No delays are possible once the operands have been delivered to the unit. The amount of time required from delivery of the operands to the unit to the completion of the calculation is termed the "functional unit time" and is measured in 12.5 nsec clock periods. The functional units are all fully segmented. This means that a new set of operands for unrelated computation may enter a functional unit each clock period even though the functional unit time may be more than one clock period. This segmentation is made possible by capturing and holding the information arriving at the unit or moving within the unit at the end of every clock period.

The twelve functional units can be arbitrarily assigned to four groups: address, scalar, vector, and floating point. The first three groups each acts in conjunction with one of the three primary register types, to support address, scalar, and vector modes of processing. The fourth group, floating point, can support either scalar or vector operations and will accept operands from or deliver results to scalar or vector registers accordingly.

#### FUNCTIONAL UNITS

Functional Unit	Unit Time (Clock Periods)	Instructions
Address integer add	2	030, 031
Address multiply	6	032
Scalar integer add	3	060, 061
Scalar logical	1	042 - 051
Scalar shift	2	052 - 055
	3	056, 057
Scalar leading zero/pop count	4	026
	3	027
Vector integer add	3	154 - 157
Vector logical	2	140 - 147, 175
Vector shift	4	150 - 153
Floating point add	6	062, 063, 170 - 173
Floating point multiply	7	064 - 067, 160 - 167
Floating point reciprocal	14	070, 174
Memory	7	176, 177

#### Memory field protection

Each object program has a designated field of memory. Field limits are defined by a base address register and a-limit address register. Any attempt to reference instructions or data beyond these limits results in a range error.

#### Exchange mechanism

The technique employed in the CRAY-1 to switch execution from one program to another is termed the exchange mechanism. A 16-word block of program parameters is maintained for each program. When another program is to begin execution, an operation known as an exchange sequence is initiated. This sequence causes the program parameters for the next program to be executed to be exchanged with the information in the operating registers to be saved. The operating register contents are thus saved for the terminating program and entered with data for the new program.

Exchange sequences may be initiated automatically upon occurrence of an interrupt condition or may be voluntarily

	0 2 10 12	16 18 24 31	36 40		63
	ESRB	Р		A0	
n + 1	RA	ВА	VA	A1	
n+1		LA	M	A2	
2		XA VL F		A3	
4		///////////////////////////////////////	TTA	A4	
			TIA	A5	
1+5			IIA	A6	
n+0			III	A7	
n + 7		SC	)		
1+0		S1			
n+9		SZ	2	and the street	
n + 10		S	3		
n + 11		S4	4		
n + 12		St	5		
n + 13		Se	3		
n + 14	The second second	S	7		

Registers

#### M - Modes<sup>†</sup>

36	Interrupt on correctable	S	Syndrome bits
	memory error	RAB	Read address for error
37	Interrupt on floating point		(where B is bank)
38	Interrupt on uncorrectable	Р	Program address
	memory error	BA	Base address
39	Monitor mode	LA	Limit address
		XA	Exchange address
	F - Flags <sup>†</sup>	VL	Vector length
31	Console interrupt		
32	RTC interrupt		E - Error type (bits 0,1)
33	Floating point error	10	Uncorrectable memory
34	Operand range	01	Correctable memory
35	Program range		Confectable memory
36	Memory error		B - Bead mode (hits 10 11)
37	I/O interrupt	00	C la
38	Error exit	00	Scalar
39	Normal exit	01	1/0
-		10	Vector
Bit	position from left of word	11	retch

#### **EXCHANGE PACKAGE**

initiated by the user or by the operating system through normal and error exit instructions.

#### Clock period counter

Programs can be precisely timed with a real-time clock period counter that increments once each 12.5 nanoseconds.

#### Programmable real-time clock

As a special option, the CRAY-1 may be equipped with a programmable real-time clock that has a frequency of 10 MHz and an increment of 100 nanoseconds.

#### SOFTWARE

The CRAY-1, as with any other computer system, requires three types of software: an operating system, language/utility systems, and applications programs.

#### The Operating System

The CRAY Operating System is a group of memory or disk resident programs that manages the resources, supervises the running of jobs, and performs input/output operations.

The operating system is activated through a system dead start operation performed from the MCU. A job usually consists of compilation of a program written in some language such as FORTRAN, loading and execution of the program generated by the compiler, and processing of all output data generated by the job.

The operating system is purposely straight-forward and uncomplicated to keep system overhead low. The operating system is multiprogrammed so that a large number of jobs can be in some stage of processing concurrently. Jobs are submitted by front-end (host) computers or at local or remote job entry stations. A job waits on mass storage until the operating system determines that the resources it requires are available. At this time, the sytem begins processing the job by examining each of the control statements that accompany the job deck and are used to inform the operating system of the tasks to be performed by the job. The control statements are read, interpreted, and acted on sequentially. Output from a job is placed on system mass storage. At job completion, this output may be transferred back to the front-end computer or station of job origin for processing such as printing or transfer to magnetic tape.

If a job is waiting for resources, operator action, data transfer, or some other action, the operating system may move the job onto mass storage (roll it out) so that some other job can be executed. Job flow is depicted on page 8.

Features of the operating system include the following:

- Resource management
- Remote or local job entry
- Multiprogramming of jobs
- Management of data sets that survive from one dead start to another (permanent data sets)
- Generation of a chronological history of each job called a log file. It lists each control statement and any problems encountered.
- Communication with station operators
- Staging of data sets between system mass storage and peripheral devices such as magnetic tape units.

#### **FORTRAN** compiler

Developed in parallel with the CRAY-1 computer system is a powerful FORTRAN compiler designed to take advantage of the vector capability of the computer.

The compiler, itself, determines the need for vectorizing and generates code accordingly removing the burdens of such considerations from the programmer. A significant effort is being made to develop optimizing routines that examine FORTRAN code to see if it can be vectorized. The compiler adheres closely to the ANSI 1966 standard.

#### Assembler

The Cray Research, Inc. CAL assembler provides users with a

means of expressing symbolically all hardware functions of the CPU. Augmenting the instruction repertoire is a set of versatile pseudo instructions that provide users with options for generating macro instructions, organizing programs, and so on.

CAL enables the user to tailor programs to the architecture of the CRAY-1. The operating system as well as most other software provided by Cray Research, Inc. is coded in CAL assembly language.

#### Source program maintenance

An UPDATE program provides a means of maintaining source language programs as card images on mass storage or on magnetic tape. The user converts the source language program to a data set called a library in which each of the original cards is assigned a number. Later, when the user wishes to modify the card, it is referenced by its number and is accordingly deleted, replaced, or used for an insertion point of additional



DATA FLOW THROUGH SYSTEM

cards. After being corrected, the edited program can be submitted to the FORTRAN compiler or CAL assembler for processing. Corrections can be temporary for the purpose of testing new code or can be permanent.

#### Front-end systems

A variety of computer systems produced by other manufacturers may serve as front-end systems to the CRAY-1. A minimum of one such system is expected to be present. A front-end system may serve as a job entry station for submitting jobs to the CRAY-1 and processing output from jobs or as a data concentrator for multiplexing several remote stations or terminals. In addition, a front-end system may provide operator functions by passing commands and messages between the CRAY-1 and the operator at the front-end system.

A front-end system operates under control of its own operating system in a mode asynchronous to the CRAY-1 computer system. The MCU when not used for monitor purposes can serve in the capacity of a front-end computer system.

#### Applications programs

Applications programs are specialized programs usually written in a source language such as FORTRAN that solve particular user problems. These programs are generally written by customers. Cray Research, Inc. will provide software specialists on a contractual basis to assist customers in the preparation and development of specific applications programs.

#### ARCHITECTURE

#### Construction

The CRAY-1 with 16 memory banks is modularly constructed of 1662 modules held by 24 chassis. Each module contains two 6 in. by 8 in. printed circuit boards on which are mounted a maximum of 144 integrated circuit packages per board. Emitter coupled logic (ECL) is used throughout. Four basic chip types are used: a high-speed 5/4 NAND gate, a slow-speed 5/4 NAND gate, a 16x1 register chip, and a 1024x1 memory chip.

#### Appearance

The aesthetics of the machine have not been neglected. The CPU is attractively housed in a cylindrical cabinet. The chassis are arranged two per each of the twelve wedge-shaped columns. At the base are the twelve power supplies. The power supply cabinets, which extend outward from the base are vinyl padded to provide seating for computer personnel.

The compact mainframe occupies a mere 70 sq. ft. of floor space.

#### Cooling

The speed of the CPU is derived largely by keeping wire lengths extremely short in the mainframe. This, in turn, necessitates a dense concentration of components with an accompanying problem of heat dissipation. The Freon cooling system used in the CRAY-1 employs the latest in refrigeration technology to maintain a column temperature of about  $68^{\circ}$  in the unit.

#### MAINTENANCE CONTROL UNIT (MCU)

A 16-bit minicomputer system serves as a maintenance control unit. The MCU performs system initialization and basic recovery for the operating system. Included in the MCU system is a software package that enables the minicomputer to monitor CRAY-1 performance during production hours.

#### EXTERNAL INTERFACE

The CRAY-1 may be interfaced to front-end host systems through special controllers that compensate for differences in channel widths, machine word size, electrical logic levels, and control protocols. The interface is a Cray Research, Inc. product implemented in logic compatible with the host system.

#### SYSTEM MASS STORAGE

System mass storage consists of two or more Cray Research, Inc. DCU-2 Disk Controllers and multiple DD-19 Disk Storage Units. The disk controller is a Cray Research, Inc. product and is implemented in ECL logic similar to that used in the mainframe. Each controller may have four DD-19 disk storage units attached to it. Operational characteristics of the DD-19 units are summarized in the accompanying table.

#### CHARACTERISTICS OF DD-19 DISK STORAGE UNIT

Bit capacity per drive	2.424 × 10 <sup>9</sup>
Tracks per surface	411
Sectors per track	18
Bits per sector	32,768
Number of head groups	10
Recording surfaces per drive	40
Latency	16.6 msec
Access time	15 - 80 msec
Data transfer rate (average bits per sec.)	35.4 x 10 <sup>6</sup>
Total bits that can be streamed to a unit (disk cylinder capacity)	5.9 x 10 <sup>6</sup>

#### MAINTENANCE SERVICES

Cray Research, Inc. provides resident maintenance engineers on a contractual basis.

### **CRAY-1 INSTRUCTION SET**

CRAY-1	CAL		DESCRIPTION	CRAY-1	CAL		DESCRIPTION
000xxx	ERR		Error exit	062ijk	Si	Sj+FSk	Floating sum of (Sj) and (Sk) to Si
†000ijk	ERR	exp	Error exit	+062i0k	Si	+FSk	Normalize (Sk) to Si
0010jk	CA,Aj	Ak	Set the channel (Aj) current address to	063ijk	Si	Sj-FSk	Floating difference of (Sj) and (Sk) to Si
001142	CT 14	AL	(AK) and begin the 1/0 sequence	+063i0k	Si	-FSk	Transmit normalized negative of (Sk) to Si
001210	CT A:	AK	Clear channel (A) limit address to (AK)	064ijk	Si	Sj*FSk	Floating product of (Sj) and (Sk) to Si
0012jx 0013jx	XA	Aj	Enter XA register with (Aj)	065ijk	Si	Sj*HSk	Half precision rounded floating product of (Sj) and (Sk) to Si
0014jx	RT	Sj	Enter real-time clock register with (Sj)	066ijk	Si	Sj*RSk	Full precision rounded floating product of (Si) and (Sk) to Si
OUZOXK	VL	Ak	Transmit (Ak) to VL register	067iik	Si	Si*ISk	2 - Floating product of (Si) and (Sk) to Si
T0020X0	VL	1	Transmit 1 to VL register	070ijx	Si	/HS1	Floating reciprocal approximation of
0021xx	EFI		Enable interrupt on floating point error			1	(Sj) to Si
0022xx	DFI		Disable interrupt on floating point error	071i0k	Si	Ak	Transmit (Ak) to Si with no sign extension
003xjx	VM	Sj	Transmit (Sj) to VM register	071i1k	Si	+Ak	Transmit (Ak) to Si with sign extension
+003x0x 004xxx	EX	0	Clear VM register Normal exit	071i2k	Si	+FAk	Transmit (Ak) to Si as unnormalized floating point number
†004ijk	EX	exp	Normal exit	071i3x	Si	0.6	Transmit constant 0.75*2**48 to Si
005xjk	J	Bjk	Jump to (Bjk)	071i4x	Si	0.4	Transmit constant 0.5 to Si
006ijkm	J	exp	Jump to exp	071i5x	Si	1.	Transmit constant 1.0 to Si
007ijkm	R	exp	Return jump to exp; set B00 to P	071i6x	Si	2.	Transmit constant 2.0 to Si
010ijkm	JAZ	exp	Branch to exp if $(A0) = 0$	071i7x	Si	4.	Transmit constant 4.0 to Si
011ijkm	JAN	exp	Branch to exp if (A0) $\neq 0$	072ixx	Si	RT	Transmit (RTC) to Si
012ijkm	JAP	exp	Branch to exp if (A0) positive	073ixx	Si	VM	Transmit (VM) to Si
013ijkm	JAM	exp	Branch to exp if (A0) negative	074iik	Si	Tik	Transmit (Tik) to Si
014ijkm	JSZ	exp	Branch to exp if $(S0) = 0$	075iik	Tik	Si	Transmit (Si) to Tik
015ijkm	JSN	exp	Branch to exp if $(S0) \neq 0$	0761jk	Si	Vi.Ak	Transmit (Vi, element (Ak)) to Si
016ijkm	JSP	exp	Branch to exp if (SO) positive	077iik	Vi.Ak	Si	Transmit (Si) to Vi element (Ak)
017ijkm	JSM	exp	Branch to exp if (SO) negative	+077i0k	Vi.Ak	0	Clear Vi element (Ak)
020ijkm			Transmit exp = jkm to Ai	10hiikm	Ai	exp.Ah	Read from $((\Delta h) + exp)$ to $\Delta i (\Delta 0=0)$
021ijkm	Ai	exp	Transmit exp = 1's complement of ikm to Ai	+100ijkm	Ai	exp,0	Read from (exp) to Ai
022ijk			Transmit exp = jk to Ai	+100ijkm	Ai	exp,	Read from (exp) to Ai
023ijx	Ai	Si	Transmit (Si) to Ai	+10hi000	Ai	, Ah	Read from (Ah) to Ai
024iik	Ai	Bik	Transmit (Bik) to Ai	11hijkm	exp,Ah	Ai	Store (Ai) to (Ah) + exp (A0=0)
025iik	Bik	Ai	Transmit (Ai) to Bik	†110ijkm	exp,0	Ai	Store (Ai) to exp
026iix	Ai	PSi	Population count of (Si) to Ai	†110ijkm	exp,	Ai	Store (Ai) to exp
027ijx	Ai	ZSi	Leading zero count of (Si) to Ai	+11hi000	,Ah	Ai	Store (Ai) to (Ah)
030iik	Ai	Ai+Ak	Integer sum of (Aj) and (Ak) to Ai	12hijkm	Si	exp,Ah	Read from ((Ah) + exp) to Si (A0=0)
+030i0k	Ai	Ak	Transmit (Ak) to Ai	†120ijkm	Si	exp,0	Read from exp to Si
+0301i0	Ai	Ai+1	Integer sum of (Ai) and 1 to Ai	†120ijkm	Si	exp,	Read from exp to Si
0311jk	Ai	Aj-Ak	Integer difference of (Aj) less (Ak) to Ai	+12hi000	Si	, Ah	Read from (Ah) to Si
+031100	Ai	-1	Transmit -1 to Ai	13hijkm	exp,Ah	Si	Store (Si) to (Ah) + exp (A0=0)
031i0k	Ai	-Ak	Transmit the negative of (Ak) to Ai	+130ijkm	exp,0	Si	Store (Si) to exp
031110	Ai	Ai-1	Integer difference of (Ai) less 1 to Ai	†130ijkm	exp,	Si	Store (Si) to exp
032ijk	Ai	Ai*Ak	Integer product of (Ai) and (Ak) to Ai	+13hi000	,Ah	Si	Store (Si) to (Ah)
03310x	Ai	CT	Channel number to Ai (i=0)	140ijk	Vi	Sj&Vk	Logical products of (Sj) and (Vk) to Vi
033110	Ai	CA AI	Address of channel (Ai) to Ai $(i \neq 0, k=0)$	+140i00	Vi	0	Clear Vi
033111	Ai	CE Ai	Error flag of channel (Ai) to Ai ( $i \neq 0$ , $k = 1$ )	141ijk	Vi	Vj&Vk	Logical products of (Vj) and (Vk) to Vi
034111	Rik Ai	A0	Read (Ai) words to B register ik from (AO)	142ijk	Vi	Sj!Vk	Logical sums of (Sj) and (Vk) to Vi
+034ijk	Bik Ai	0.40	Read (Ai) words to B register ik from (A0)	+142i0k	Vi	Vk	Transmit (Vk) to Vi
035jik	. 40	Bik Ai	Store (Ai) words at B register ik to (A0)	143ijk	Vi	Vj!Vk	Logical sums of (Vj) and (Vk) to Vi
the second se			THE PART OF A PA				

							1 1
+035ijk	0,A0	Bjk,Ai	Store (Ai) words at B register jk to (A0)	144ijk	Vi	Sj∖Vk	Logical differences of (Sj) and (Vk) to Vi
036ijk	Tjk,Ai	,A0	Read (Ai) words to T register jk from (AO)	145ijk	Vi	Vj\Vk	Logical differences of (Vj) and (Vk) to Vi
+036ijk 037iik	Tjk,Ai	0,A0 Tik.Ai	Read (Ai) words to T register jk from (A0) Store (Ai) words at T register ik to (A0)	146ijk	Vi	Sj!Vk&VM	Transmit (Sj) if VM bit = 1; (Vk) if VM bit = 0 to Vi
†037ijk	0.40	Tik.Ai	Store (Ai) words at T register ik to (A0)	+146i0k	Ví	#VM&Vk	Vector merge of (Vk) and 0 to Vi
040ijkm	lsi	exp	Transmit jkm to Si	147ijk	Vi	Vj!Vk&VM	Transmit (Vj) if VM bit = 1; (Vk) if VM bit = 0 to Vi
041ijkm	1	ent	Transmit exp = 1's complement of jkm to Si	150ijk	Vi	Vj <ak< td=""><td>Shift (Vj) left (Ak) places to Vi</td></ak<>	Shift (Vj) left (Ak) places to Vi
042ijk	Si	<exp< td=""><td>Form 1's mask exp = 64-jk bits in Si from</td><td>+150ij0</td><td>Vi</td><td>Vj&lt;1</td><td>Shift (Vj) left one place to Vi</td></exp<>	Form 1's mask exp = 64-jk bits in Si from	+150ij0	Vi	Vj<1	Shift (Vj) left one place to Vi
	Si	#>exp	the right	151ijk	Vi	Vj>Ak	Shift (Vj) right (Ak) places to Vi
+042177	Sí	1	Enter 1 into Si	†151ij0	Vi	Vj>1	Shift (Vj) right one place to Vi
+042100	Si	-1	Enter -1 into Si	152ijk	Vi	Vj,Vj <ak< td=""><td>Double shift (Vj) left (Ak) places to Vi</td></ak<>	Double shift (Vj) left (Ak) places to Vi
043ijk	Si	>exp #sexp	Form 1's mask exp = jk bits in Si from	+152ij0	Vi	Vj,Vj<1	Double shift (Vj) left one place to Vi
+043100	Si	0	Clear Si	153ijk	Vi	Vj,Vj>Ak	Double shift (Vj) right (Ak) places to Vi
044iik	Si	Sissk	logical product of (Si) and (Sk) to Si	153ij0	Vi	Vj,Vj>1	Double shift (Vj) right one place to Vi
+044 1 10	Si	Sigsr	Sign bit of (Si) to Si	154ijk	Vi	Sj+Vk	Integer sums of (Sj) and (Vk) to Vi
+044110	Si	SB&Si	Sign bit of $(Si)$ to Si $(i \neq 0)$	155ijk	Vi	Vj+Vk	Integer sums of (Vj) and (Vk) to Vi
+045iik	Si	#Skesi	Logical product of (Si) and 1's	156ijk	Vi	Sj-Vk	Integer differences of (Sj) and (Vk) to Vi
		-ondo)	complement of (Sk) to Si	+156i0k	Vi	-Vk	Transmit negative of (Vk) to Vi
†045ij0	Si	#SB&Sj	(Sj) with sign bit cleared to Si	157ijk	Vi	Vj-Vk	Integer differences of (Vj) and (Vk) to Vi
046ijk	Si	Sj\Sk	Logical difference of (Sj) and (Sk) to Si	160ijk	Vi	Sj*FVk	Floating products of (Sj) and (Vk) to Vi
+046ij0	Si	Sj∖SB	Toggle sign bit of Sj, then enter into Si	161ijk	Vi	Vj*FVk	Floating products of (Vj) and (Vk) to Vi
+046ij0	Si	SB\Sj	Toggle sign bit of Sj, then enter into Si $(j \neq 0)$	162ijk	Vi	Sj*HVk	Half precision rounded floating products of (Si) and (Vk) to Vi
00/1jk	51	#SJ\SK	Logical equivalence of (Sk) and (Sj) to Si	163iik	Vi	Vi*HVk	Half precision rounded floating products
104/10K	51	f SK	Transmit I's complement of (SK) to Si				of (Vj) and (Vk) to Vi
104/130	51	#SJ\SB	Logical equivalence of (Sj) and sign bit to Si	164ijk	Vi	Sj*RVk	Rounded floating products of (Sj) and (Vk) to Vi
7047130	S1	#SBNSj	Logical equivalence of (Sj) and sign bit to Si $(j\neq 0)$	165ijk	Vi	Vj*RVk	Rounded floating products of (Vj) and (Vk) to Vi
704/100	51	#SB	Enter 1's complement of sign bit into Si	166ijk	Vi	Sj*IVk	2 - floating products of (Sj) and
050ijk	Si	Sj!Si&Sk	Logical product of (Si) and (Sk) complement ORed with logical product of (Sj) and (Sk) to Si	167ijk	Vi	Vj*IVk	<pre>(Vk) to Vi 2 - floating products of (Vj) and</pre>
+050ij0	Si	Sj!Si&SB	Scalar merge of (Si) and sign bit of (Sj)	170111	117	C1. P10	(Vk) to Vi
051111	S i	Silsk	Logical sum of (Si) and (Sk) to Si	1701JK	VI	SJ+FVK	Floating sums of (5)) and (VK) to Vi
+051101	Si	Sk.	Tranemit (Sk) to Si	TITUIUK	V1	+FVK	Normalize (VK) to Vi
+051110	Si	Si'SB	Logical sum of (Si) and sign hit to Si	1/11jx	V1	VJ+FVK	Floating sums of (V) and (Vk) to Vi
+051110	Ci	SRISI	logical sum of $(Si)$ and sign bit to Si $(i40)$	1/21]K	V1	SJ-FVK	Transmit normalized monthing of (VL) to VI
+051100	Si	SR	Enter sign bit into Si	1771UK	V1	- FVK	Thansmit hormalized negatives of (VK) to VI
0521100	SO	Sizern	Shift (Si) loft own = it places to CO	1/3138	V1 V2	VJ-FVK	Floating differences of (vj) and (vk) to vi
OSTIIK	50	Sisevn	Shift (Si) right $axp = 64$ ik places to S0	1/41JX	VI	/HVJ	(Vj) to Vi
05411k	Si	Sizern	Shift (Si) left exp = it places	175xj0	VM	Vi.Z	VM=1 where $(Vj) = 0$
055111	Si	Sibern	Shift (Si) right exp = 64-ik places	175xj1	VM	Vj.N	$VM=1$ where $(Vj) \neq 0$
056111	Si	Si SieAk	Shift (Si and Si) left (Ak) places to Si	175xj2	VM	Vj.P	VM=1 where (Vj) positive
t056110	Si	Si.Sidl	Shift (Si and Si) left one place to Si	175xj3	VM	Vj.M	VM=1 where (Vj) negative
+05610k	Si	SisAk	Shift (Si) left (Ak) places to Si	176ixk	Vi	,A0,Ak	Read (VL) words to Vi from (A0)
057iik	Si	Si.Si Ak	Shift (Si and Si) right (Ak) places to Si				incremented by (Ak)
+057110	Si	Si.Si>1	Shift (Si and Si) right one place to Si	+176ix0	Vi	,A0,1	Read (VL) words to Vi from (A0)
+05710k	Si	Si>Ak	Shift (Si) right (Ak) places to Si	177841	40 AF	Vi	Store (VI) words from Vi to (A0)
060iik	Si	Si+Sk	Integer sum of (Si) and (Sk) to Si	TUNIK	,AU,AK	0	incremented by (Ak)
061ijk	Si	Sj-Sk	Integer difference of (Si) and (Sk) to Si	+177xj0	,A0,1	Vj	Store (VL) words from Vj to (AO)
+061i0k	Si	-Sk	Transmit negative of (Sk) to Si				incremented by 1

† Special CAL syntax format

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